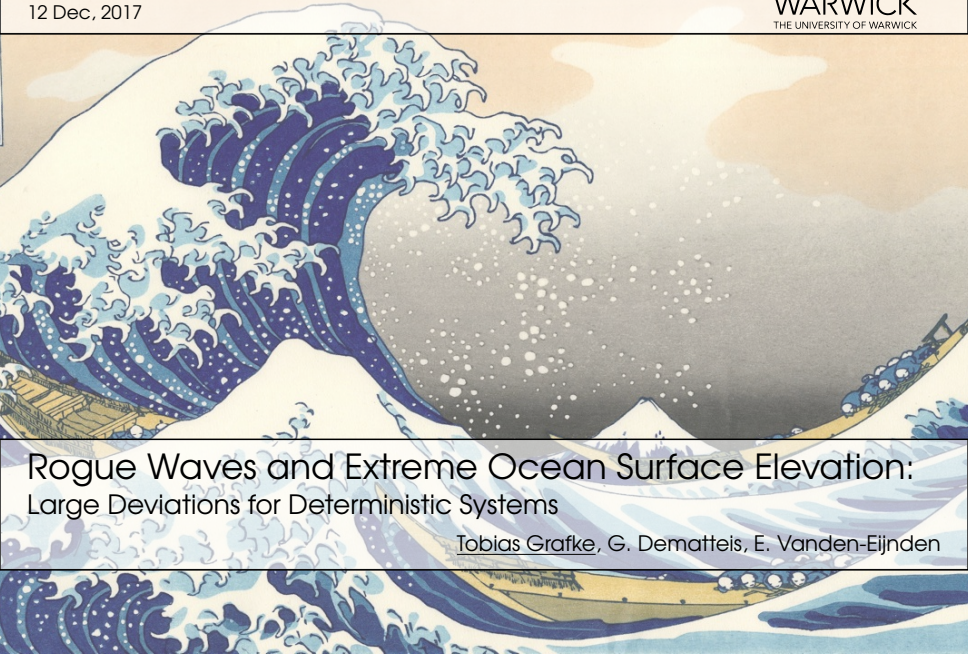


*Wave Turbulence in Nonlinear Optics, BECs, and Related Areas*

Aston University, Birmingham

12 Dec, 2017



# Rogue Waves and Extreme Ocean Surface Elevation: Large Deviations for Deterministic Systems

Tobias Grafke, G. Dematteis, E. Vanden-Eijnden

## Rogue waves:

Events of extreme ocean surface elevation.

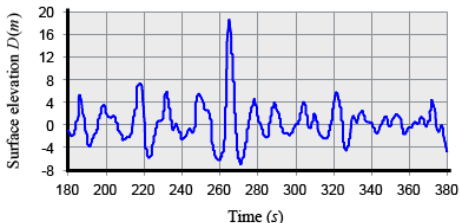
- Mechanism not fully understood
- Probably caused by **nonlinear amplification** (*modulational instability*) out of a background of (smaller) waves
- Probability density function unknown.

Goal: Estimate **tails** of the distribution



Tanker "Stolt Surf" in 1977, New York Times

January 1 1995 at 15:20,  $h_s = 11.9\text{m}$

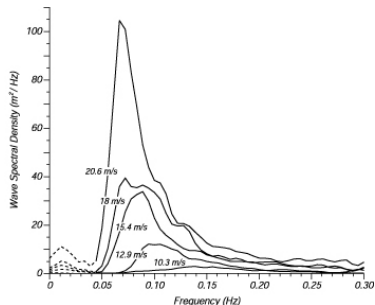


"Draupner Wave", Jan 1, 1995

# Extreme events in fluid dynamics: Rogue waves

Two basic ingredients:

- **Random data** from **observations** as input (*prior*)
- Accurate **dynamical system** to extrapolate output (*posterior*)



Wave height observation

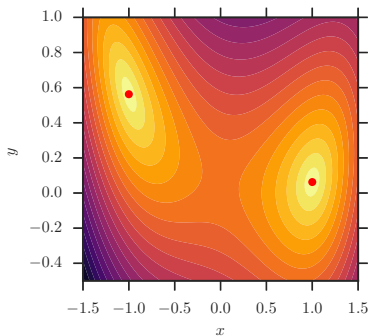


Wave channel, TU Hamburg

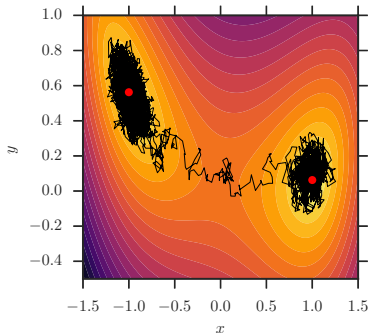
Estimate **probabilities** of **extreme events** via **large deviation theory**

- The way rare events occur is often predictable — it is dominated by the *least unlikely* scenario — which is the essence of LDT
- Calculation of the least unlikely scenario (maximum likelihood pathway, MLP) reduces to a deterministic optimization problem

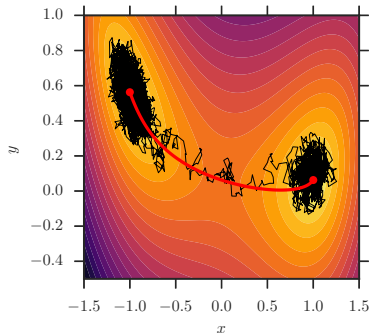
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- Simple example: gradient systems (navigating a potential landscape), transitions between local energy minima happen through minimum energy paths (mountain pass transition)



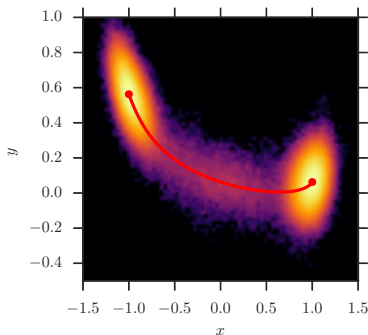
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Consider the S(P)DE

$$dX^\varepsilon(t) = b(X^\varepsilon(t)) dt + \sqrt{\varepsilon}\sigma(X^\varepsilon(t)) dW(t)$$

Then, the LDT **rate function** is

$$\mathcal{I}_T(\phi) = \frac{1}{2} \int_0^T \left| \sigma(\phi)^{-1} \left( \dot{\phi} - b(\phi) \right) \right|^2 dt = \frac{1}{2} \int_0^T \mathcal{L}(\phi, \dot{\phi}) dt$$

The probability that  $\{X^\varepsilon(t)\}_{t \in [0, T]}$  is close to a path  $\{\phi(t)\}_{t \in [0, T]}$  is

$$\mathcal{P} \left\{ \sup_{0 \leq t \leq T} |X^\varepsilon(t) - \phi(t)| < \delta \right\} \asymp \exp(-\varepsilon^{-1} \mathcal{I}_T(\phi)) \text{ for } \varepsilon \rightarrow 0$$

The problem is reduced to a **minimization** problem

$$\mathcal{P} \{F(X^\varepsilon(T)) = z | X^\varepsilon(0) = x\} \asymp \exp \left( -\varepsilon^{-1} \inf_{\phi: \phi(0)=x, F(\phi(T))=z} \mathcal{I}_T(\phi) \right)$$

Minimizer  $\phi^*$  is called **instanton**

# Example: Ornstein-Uhlenbeck

## Ornstein-Uhlenbeck process

$$du = b(u) dt + dW, \quad b(u) = -\gamma u, \quad \gamma > 0.$$

Consider extreme events with  $u(T) = z$   
(so  $F(u) = u(T)$ ).

The **instanton** is

$$u^*(t) = ze^{\gamma(t-T)} \left( \frac{1 - e^{-2\gamma t}}{1 - e^{-2\gamma T}} \right),$$

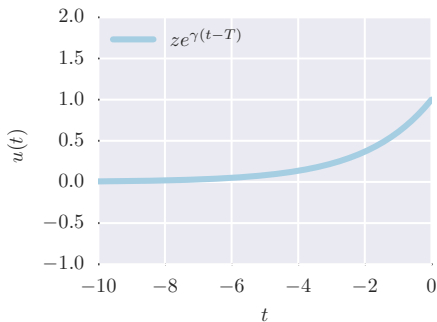
obtained from **constrained optimization**

$$\inf_{\{u_t\} \in \mathcal{U}_z} \mathcal{I}_T(z) = \inf_{\{u_t\} \in \mathcal{U}_z} \frac{1}{2} \int_0^T |\dot{u} + \gamma u|^2 dt$$

over the set

$$\mathcal{U}_z = \left\{ \{u_t\} \mid F(u_T) = z \right\}$$

Yields **optimal fluctuations** to realize event.



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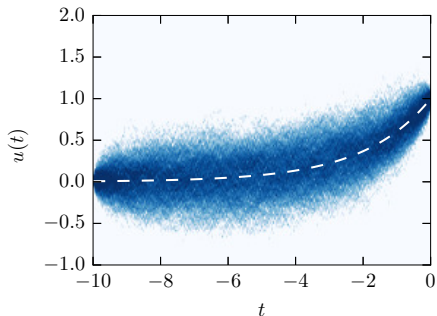
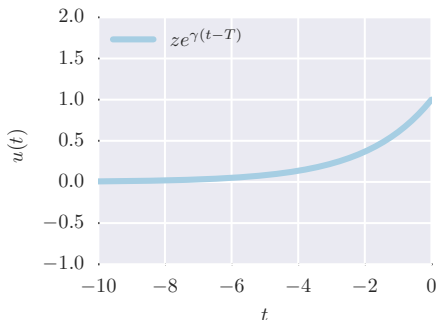
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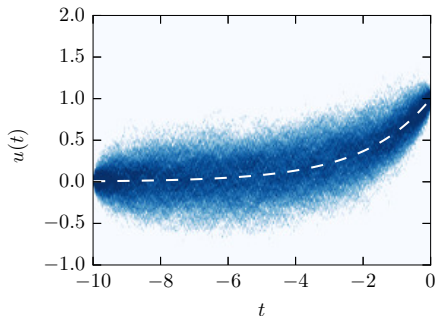
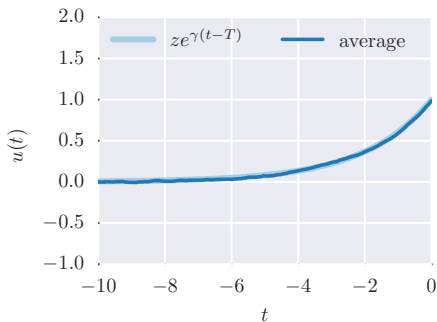
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Evolution of a narrow-banded, uni-directional **wave envelope**  $u(t, x)$  on the surface of a fluid with **infinite depth**:

*modified nonlinear Schrödinger equation* (MNLS) or *Dysthe's equation*

$$\partial_t u + \frac{1}{2} \partial_x u + \frac{i}{8} \partial_x^2 u - \frac{1}{16} \partial_x^3 u + \frac{i}{2} |u|^2 u + \frac{3}{2} |u|^2 \partial_x u + \frac{1}{4} u^2 \partial_x u^* - \frac{i}{2} |\partial_x u|^2 = 0$$

on domain  $x \in \Omega$  with **sea surface elevation**  $\eta(t, x) = \text{Re}(u(t, x)e^{i(k_0 x - \omega_0 t)})$

- Equation for  $u(t, x)$  is deterministic
- Initial conditions  $u_0(x) \equiv u(0, x)$  are random
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## Central assumption

The **initial distribution** evolves on **long timescales** through forcing (wind) and damping, defining a random background out of which **rogue waves** can evolve on a **fast timescale**, where forcing and damping are negligible.

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Key difference: LDP on **initial conditions** instead of stochastic dynamics

$$\partial_t u(t) = b(u(t)), \quad u(0) = u_0 \sim \mu_0 \asymp \exp(-\varepsilon^{-1}G(u_0))$$

Given **observable**  $F(u(T))$ , we are interested in

$$P_T(z) = \mathcal{P}\{F(u(T)) \geq z\},$$

and extreme events via **LDP** for its density  $\rho_T(z) = dP_T(z)/dz$ ,

$$\rho_T(z) \asymp \exp(\varepsilon^{-1}\mathcal{I}_T(z)).$$

Define **cumulant generating function**

$$\varepsilon \log \mathbb{E}_{\mu_0} e^{\lambda \varepsilon^{-1} F(u(T))} \sim \sup_{u_0 \in \mathcal{U}} \{\lambda F(u(T)) - G(u_0)\} \equiv S_T(\lambda)$$

Then, by the *Gärtner-Ellis* theorem,  $\mathcal{I}_T(z)$  is the Fenchel-Legendre transform of  $S_T(\lambda)$ ,

$$S_T(\lambda) = \sup_{z \in \mathbb{R}} (\lambda z - \mathcal{I}_T(z))$$

and therefore

$$\mathcal{I}_T(z) = \inf_{u_0: F(u(T))=z} G(u_0)$$



Define the **Jacobian**  $J(t, u_0) = \frac{\delta u(t)}{\delta u_0}$  where  $u(0) = u_0$ .

- Solve **constrained optimization** through descent,

$$\frac{\delta S_T}{\delta u_0} = \frac{\delta G(u_0)}{\delta u_0} - \lambda J^T(T, u_0) \frac{\delta F}{\delta u}$$

- The Jacobian evolves according to

$$\dot{J}(t, u_0) = \frac{\delta b(u(t, u_0))}{\delta u} J(t, u_0), \quad J(0, u_0) = Id$$

- Repeat calculation for various  $\lambda$  to estimate  $S_T(\lambda)$ , and thus  $\mathcal{I}_T(z)$  and **probability**  $P_T(z)$ .
- Instanton  $u_0^*$  gives the **most likely event** leading to **rogue wave** of height  $z$ , where

$$u_0^* = \operatorname{argmax}_{u_0 \in \mathcal{U}} \{G(u_0) - \lambda F(u(T, u_0))\}$$

For **ocean surface waves** described by MNLS:

$$\partial_t u + \frac{1}{2} \partial_x u + \frac{i}{8} \partial_x^2 u - \frac{1}{16} \partial_x^3 u + \frac{i}{2} |u|^2 u + \frac{3}{2} |u|^2 \partial_x u + \frac{1}{4} u^2 \partial_x u^* - \frac{i}{2} |\partial_x u|^2 u = 0$$

- Initial distribution **Gaussian** and approximates JONSWAP spectrum,

$$G(u_0) = \frac{1}{2} \langle u_0, C^{-1} u_0 \rangle$$

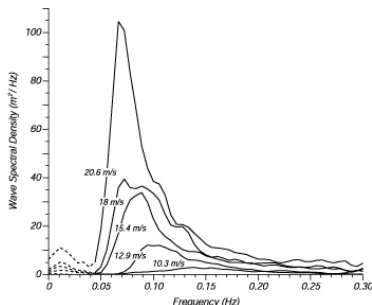
(but other forms are possible)

- Pick as **observable**

$$F(u(T)) = \max_{x \in \Omega} |u(T, x)| = \max_{x \in \Omega} \eta(T, x)$$

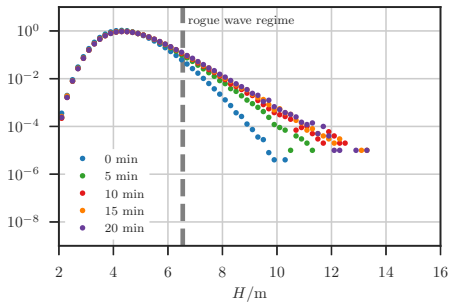
the maximum sea surface elevation at final time  $t = T$ .

JONSWAP spectrum

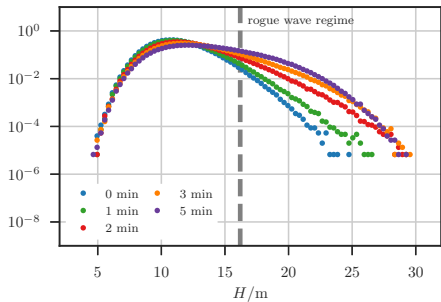


# Large deviations for random initial data: Rogue waves

*rough sea* ( $H_s = 3.3\text{m}$ ,  $\text{BFI} = 0.34$ )

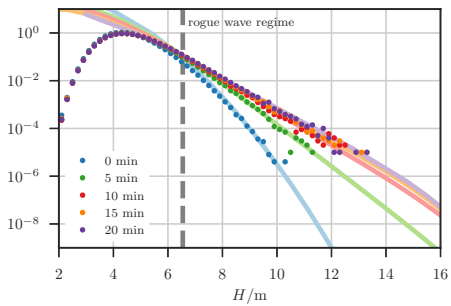


*high sea* ( $H_s = 8.2\text{m}$ ,  $\text{BFI} = 0.85$ )

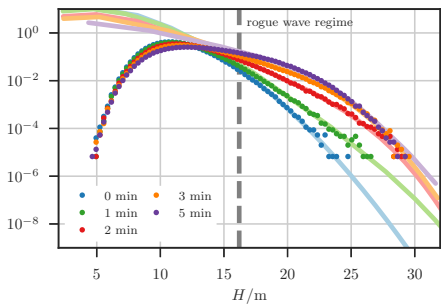


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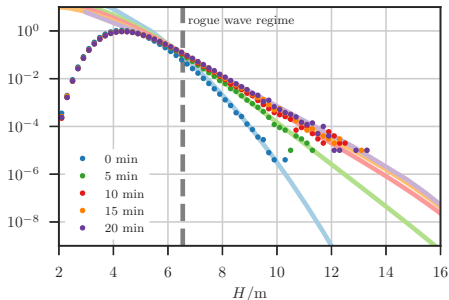


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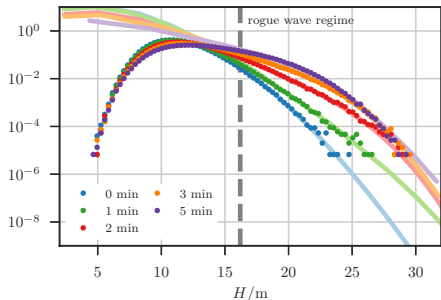


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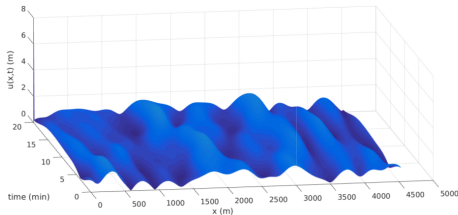
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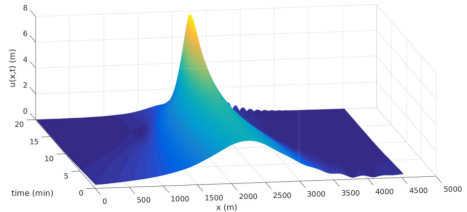
Comparison between **Monte Carlo** (dots) and **LDT** (lines):

- LDT is able to **predict tails** of **rogue wave** distribution.
- **PDF converges** for  $T \rightarrow 20\text{min}$  (left) and  $T \rightarrow 5\text{min}$  (right).  
(corresponds to timescales associated with **modulational instability**)
- This is the timescale after which the initial distribution is converged to the **invariant measure**, and the **extreme event tails** are correctly predicted.

# Rogue wave instantons



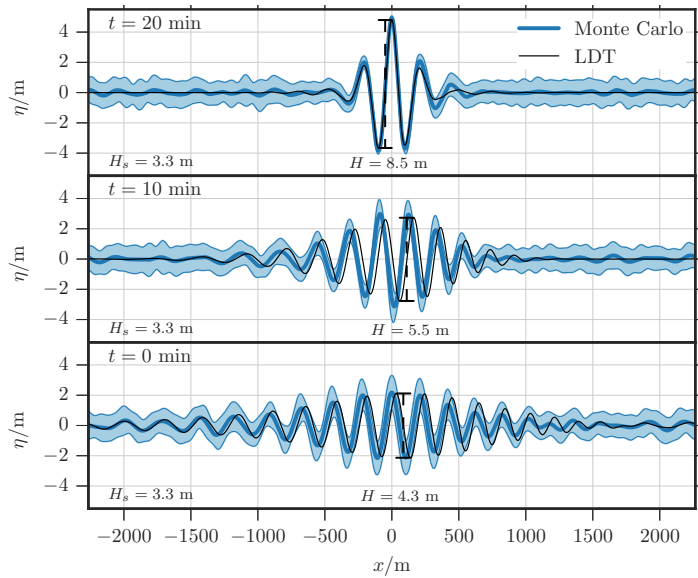
*(random initial condition: standard event)*



*(optimized initial condition: instanton)*

- Evolution is purely **deterministic**
- Only operation done here is **pick initial condition**, either at **random** (left) or **optimized** (right)

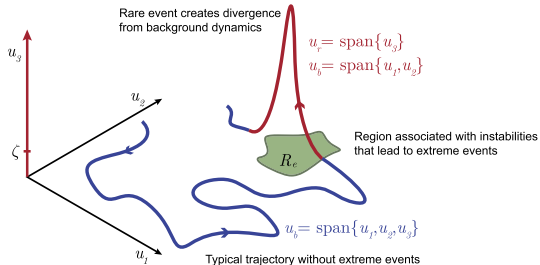
# Large deviations for random initial data: Rogue waves



G. Dematteis, T. Grafke, E. Vanden-Eijnden, PNAS 2017 (to appear), arXiv:1704.01496

# Intermittency and extreme events

- Consistent with picture but forward by Sapsis *et al.* for **intermittency** in dynamical systems
- Assumption: extreme excursions occur when dynamics hit **pockets of instability**
- Estimate **pdf tail** by measuring probability of pockets with respect to the invariant measure of background dynamics



Mohamad, Cousins, & Sapsis, J. Comp. Phys. 322 (2016) 288–308

Our approach formalizes this concept within the realm of **large deviation theory** and gives tools to explicitly compute

- tail probabilities and expectations for observables
- most likely occurrence of extreme events

Accurate knowledge of the core distribution permits prediction of its tail from deterministic dynamics!



- Initial Gaussian distribution converges to limiting distribution for large times

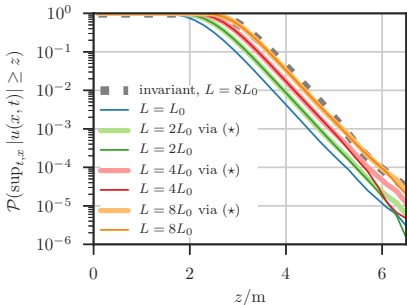
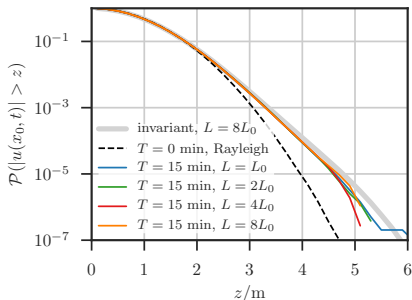
(prior  $\rightarrow$  posterior)

- Can be used to compute probability of extremes in spatio-temporal domain via **boxing argument**

$$\mathcal{P}\left(\sup_{(t,x) \in \mathcal{D}} |u(t,x)| \geq z\right) \sim 1 - (1 - \mathcal{P}(|u| \geq z))^{N_{\mathcal{D}}} \quad (*)$$

with  $N_{\mathcal{D}} = |\mathcal{D}| / (\lambda_c \tau_c)$

- Extreme events no longer **rare** if domain large enough



- Initial Gaussian distribution converges to limiting distribution for large times

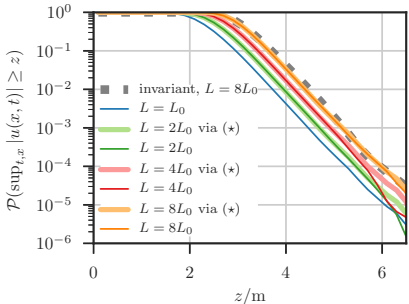
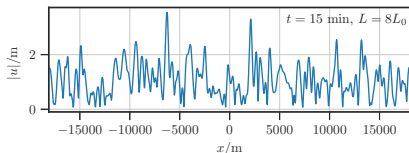
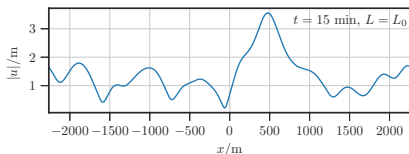
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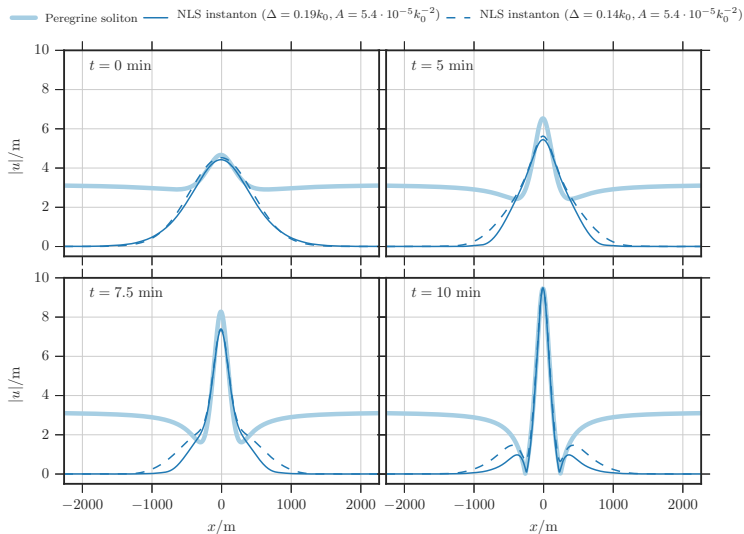
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$$u(t, x) = U_i e^{-it/T_{nl}} \left( \frac{4(1 - 2it/T_{nl})}{1 + 4(t/T_{nl})^2 + 4(x/L_{nl})^2} - 1 \right), \quad T_{nl} = \frac{2}{U_i^2}, \quad L_{nl} = \frac{1}{4} \sqrt{T_{nl}} = \frac{\sqrt{2}}{4U_i},$$

# Comparison to Peregrine soliton



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# Concluding remarks

- Twist on LDT: deterministic system (no stochastic forcing) with **random initial data** ( $\sim$  JONSWAP)
- Extreme events occurring via **instability** of the deterministic dynamics (modulational instability)
- LDT allows to estimate **probability** and **mechanism** of occurrence of rogue waves in MNLS
- Initial distribution plays a role of the **prior distribution** in Bayesian inference. Extreme event information added via short time dynamics to sample the **posterior distribution**.

